DYNAMOMETER DATA SHEET
(Version 1.1)

MODELS:

DB6B-8.7T-FM  DB6M-8.7T-FM
DB6B-8.7T-BM  DB6M-8.7T-BM

Max. continuous power dissipation:  13.2 HP (9.8 kW)
Max. Power for 30 seconds:         30 HP (22.4 kW)
Max. continuous brake torque:       424 in-lbs. (48 N-m) @ 1,000 RPM
Max. Brake Torque:                 500 in-lbs. (56.4 N-m)
Max. brake speed:                  6,000 RPM
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1. OVERVIEW

This data sheet is a reference for the performance specifications of the dynamometer models listed on the cover page.

The MBS dynamometers may be used to test just about any type of motor (i.e. electric, hydraulic, pneumatic, reciprocating). Types of testing include: endurance testing, speed versus torque curves, measure stall torque, efficiency, temperature rise, performance verification, etc. MBS dynamometers are sold as complete systems (shown in image below) that include: the dynamometer, controller, computer with software, calibration weight, manual and all cables. MBS systems do not require annual fees, licenses or permits. The software is user friendly, easily configurable (i.e. changing units, display scale limits, data acquisition rate, etc.) and has some safety precautions build in to prevent damage to the motor under test and/or the system (i.e. brake temperature sensor, setting current limit, setting power limit, trigger input signals).

The nomenclature of the dynamometer model number is described at the end of this document. The power dissipation rating for this system is located on the bottom of the cover page. This data sheet may also be used to determine the best configuration for a system.

Dynamometers, or more specifically the size of the brakes for the dynamometers, are selected based on the required power dissipation and required torque.
A belt coupled system will provide a much broader range of torque/speed supplied to the motor under test, which makes a dynamometer more cost-effective and diverse than a direct drive system. The pulleys are mounted to the brake and an idler shaft, which the motor couples to. The idler shaft strictly provides a torsional load to the motor.

There are two options in load cell configurations for this system.

**First option**: motor load cell is included (i.e. DB6M-8.7T-FM or DB6M-8.7T-BM). In this system, the operator may exchange the motor load cell as required in order to provide the highest accuracy of measurement for a specific torque range. Accuracy plots may be viewed in Section 3: Motor Torque and Speed. The brakes also have their own load cell, which the controller for the brake uses to control the torque of the brake.

The software allows the operator to switch between reading/recording the motor torque and brake torque. In some cases, such as when a motor is placed in an environmental test chamber (the dynamometer remains outside the test chamber), it may not be possible to measure the motor torque.

**Second option**: motor load cell is not included (i.e. Model DB6B-8.7T-FM or DB6B-8.7T-BM). For this system, the motor torque is calculated by measuring the brake torque and multiplying by the transmission. Though belt friction, bearing friction and any other minor losses may not be accounted for in the measurements, the bearing friction is usually negligible and a properly aligned belt may have an efficiency as high as 98%. When measuring the brake torque, the air drag from the brake is not measured; however, the dynamometer software compensates for the air drag.

The motor torque, motor speed, voltage range, current range and power type(s) (i.e. DC, AC, AC-3ph) need to be specified when purchasing a dynamometer in order to select the types and limits for the measurement instruments. The following performance specifications for load cells, transducers, etc., are based on vendor specifications.

A certified calibration weight comes with each system. The zero torque and gain are adjusted by the operator as part of the calibration procedure. Calibration takes a couple of minutes and may be performed as often as desired. Customers may use calibrated weights to simulate a specific load to check for torque accuracy.
2. SPEED vs. TORQUE CURVE – FOR ONE MB-8.7 BRAKE
3. MOTOR TORQUE & SPEED:

For a system measuring the motor torque, Tables 1 through 6 may be referenced for selecting the pulley ratios based on the required torque to the motor and motor speed. Reference Table 7 for the “L.C. Ref. #,” column. These tables show performance examples of the dynamometer; any pulley ratio in between 4:1 and 1:4 is a viable option. Note to take air drag of the brake(s) into account for the minimum torque required at speed.

3.1 Pulley Ratio’s (English Units)

<table>
<thead>
<tr>
<th>Motor Speed (RPM)</th>
<th>Motor Torque (in-lbs.)</th>
<th>Power (HP)</th>
<th>Pulley Ratio (mtr/bkr)</th>
<th>Qty. Brks</th>
<th>Brake Torque (in-lbs.)</th>
<th>Brake Speed (RPM)</th>
<th>Time (sec)</th>
<th>L.C. Ref. # **</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1,000</td>
<td>0</td>
<td>4:1</td>
<td>2</td>
<td>250</td>
<td>0</td>
<td>cont. 14</td>
<td></td>
</tr>
<tr>
<td>250</td>
<td>1,744</td>
<td>6.9</td>
<td>4:1</td>
<td>2</td>
<td>437</td>
<td>1,000</td>
<td>cont. 15</td>
<td></td>
</tr>
<tr>
<td>450</td>
<td>1,000</td>
<td>7.1</td>
<td>4:1</td>
<td>2</td>
<td>250</td>
<td>1,800</td>
<td>cont. 14</td>
<td></td>
</tr>
<tr>
<td>450</td>
<td>2,000</td>
<td>17.9</td>
<td>4:1</td>
<td>2</td>
<td>500</td>
<td>1,800</td>
<td>60</td>
<td>15</td>
</tr>
<tr>
<td>900</td>
<td>600</td>
<td>8.6</td>
<td>4:1</td>
<td>2</td>
<td>150</td>
<td>3,600</td>
<td>cont. 13</td>
<td></td>
</tr>
<tr>
<td>900</td>
<td>1,800</td>
<td>25.7</td>
<td>4:1</td>
<td>2</td>
<td>450</td>
<td>3,600</td>
<td>30</td>
<td>15</td>
</tr>
<tr>
<td>1,500</td>
<td>552</td>
<td>13.1</td>
<td>4:1</td>
<td>2</td>
<td>138</td>
<td>6,000</td>
<td>cont. 13</td>
<td></td>
</tr>
<tr>
<td>1,500</td>
<td>1,264</td>
<td>30.0</td>
<td>4:1</td>
<td>2</td>
<td>316</td>
<td>6,000</td>
<td>30</td>
<td>15</td>
</tr>
</tbody>
</table>

Table 1: Speed, Torque & Power (English Units) 4:1 Pulley Ratio

<table>
<thead>
<tr>
<th>Motor Speed (RPM)</th>
<th>Motor Torque (in-lbs.)</th>
<th>Power (HP)</th>
<th>Pulley Ratio (mtr/bkr)</th>
<th>Qty. Brks</th>
<th>Brake Torque (in-lbs.)</th>
<th>Brake Speed (RPM)</th>
<th>Time (sec)</th>
<th>L.C. Ref. # **</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>250</td>
<td>0</td>
<td>1:4</td>
<td>2</td>
<td>250</td>
<td>0</td>
<td>cont. 9</td>
<td></td>
</tr>
<tr>
<td>1,000</td>
<td>437</td>
<td>6.9</td>
<td>1:1</td>
<td>2</td>
<td>437</td>
<td>1,000</td>
<td>cont. 13</td>
<td></td>
</tr>
<tr>
<td>1,800</td>
<td>250</td>
<td>7.1</td>
<td>1:1</td>
<td>2</td>
<td>250</td>
<td>1,800</td>
<td>cont. 9</td>
<td></td>
</tr>
<tr>
<td>1,800</td>
<td>475</td>
<td>13.5</td>
<td>1:1</td>
<td>2</td>
<td>475</td>
<td>1,800</td>
<td>60</td>
<td>13</td>
</tr>
<tr>
<td>3,600</td>
<td>150</td>
<td>8.5</td>
<td>1:1</td>
<td>2</td>
<td>150</td>
<td>3,600</td>
<td>cont. 7</td>
<td></td>
</tr>
<tr>
<td>3,600</td>
<td>450</td>
<td>25.7</td>
<td>1:1</td>
<td>2</td>
<td>450</td>
<td>3,600</td>
<td>30</td>
<td>13</td>
</tr>
<tr>
<td>6,000</td>
<td>138</td>
<td>13.2</td>
<td>1:1</td>
<td>2</td>
<td>138</td>
<td>6,000</td>
<td>30</td>
<td>44</td>
</tr>
</tbody>
</table>

Table 2: Speed, Torque & Power (English Units) 1:1 Pulley Ratio

<table>
<thead>
<tr>
<th>Motor Speed (RPM)</th>
<th>Motor Torque (in-lbs.)</th>
<th>Power (HP)</th>
<th>Pulley Ratio (mtr/bkr)</th>
<th>Qty. Brks</th>
<th>Brake Torque (in-lbs.)</th>
<th>Brake Speed (RPM)</th>
<th>Time (sec)</th>
<th>L.C. Ref. # **</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>62.5</td>
<td>0</td>
<td>1:4</td>
<td>2</td>
<td>250</td>
<td>0</td>
<td>cont. 5</td>
<td></td>
</tr>
<tr>
<td>1,800</td>
<td>90.5</td>
<td>2.58</td>
<td>1:4</td>
<td>2</td>
<td>362</td>
<td>450</td>
<td>cont. 6</td>
<td></td>
</tr>
<tr>
<td>3,600</td>
<td>109</td>
<td>6.78</td>
<td>1:4</td>
<td>2</td>
<td>437</td>
<td>900</td>
<td>cont. 6</td>
<td></td>
</tr>
<tr>
<td>13,500*</td>
<td>34.4</td>
<td>8.7</td>
<td>1:4</td>
<td>2</td>
<td>162.5</td>
<td>3,375</td>
<td>cont. 3</td>
<td></td>
</tr>
<tr>
<td>13,500*</td>
<td>118.7</td>
<td>25.4</td>
<td>1:4</td>
<td>2</td>
<td>475</td>
<td>3,375</td>
<td>30</td>
<td>6</td>
</tr>
<tr>
<td>15,000*</td>
<td>42</td>
<td>10.0</td>
<td>1:3</td>
<td>2</td>
<td>125</td>
<td>5,000</td>
<td>cont. 1</td>
<td></td>
</tr>
<tr>
<td>15,000*</td>
<td>7.56</td>
<td>1.8</td>
<td>1:3</td>
<td>1</td>
<td>22.7**</td>
<td>5,000</td>
<td>cont. 1</td>
<td></td>
</tr>
</tbody>
</table>

Table 3: Speed, Torque & Power (English Units) 1:4 Pulley Ratio

* Maximum motor speed is dependent upon limits of pulleys and belt.
** See Table 7 for L.C. (Load Cell) specifications based on the number shown.
*** Minimum torque required due to air drag of brake.
### 3.2 Pulley Ratio’s (SI Units)

<table>
<thead>
<tr>
<th>Motor Speed (RPM)</th>
<th>Motor Torque (Nm)</th>
<th>Power (kW)</th>
<th>Pulley Ratio (mtr/brk)</th>
<th>Qty. Brakes</th>
<th>Brake Torque (Nm)</th>
<th>Brake Speed (RPM)</th>
<th>Time (sec)</th>
<th>L.C. Ref. # **</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>113</td>
<td>0</td>
<td>4:1</td>
<td>2</td>
<td>14.1</td>
<td>0</td>
<td>cont.</td>
<td>14</td>
</tr>
<tr>
<td>250</td>
<td>198</td>
<td>5.0</td>
<td>4:1</td>
<td>2</td>
<td>49.5</td>
<td>1,000</td>
<td>cont.</td>
<td>15</td>
</tr>
<tr>
<td>750</td>
<td>226</td>
<td>17.8</td>
<td>4:1</td>
<td>2</td>
<td>56.5</td>
<td>3,000</td>
<td>30</td>
<td>14</td>
</tr>
<tr>
<td>1,250</td>
<td>62.4</td>
<td>8.2</td>
<td>4:1</td>
<td>2</td>
<td>7.8</td>
<td>5,000</td>
<td>cont.</td>
<td>15</td>
</tr>
<tr>
<td>1,250</td>
<td>158</td>
<td>20.7</td>
<td>4:1</td>
<td>2</td>
<td>39.5</td>
<td>5,000</td>
<td>30</td>
<td>13</td>
</tr>
<tr>
<td>250</td>
<td>99.0</td>
<td>2.6</td>
<td>4:1</td>
<td>1</td>
<td>24.7</td>
<td>1,000</td>
<td>cont.</td>
<td>15</td>
</tr>
<tr>
<td>250</td>
<td>198</td>
<td>5.2</td>
<td>4:1</td>
<td>1</td>
<td>24.7</td>
<td>1,000</td>
<td>cont.</td>
<td>13</td>
</tr>
</tbody>
</table>

* Maximum motor speed is dependent upon limits of pulley and belt.

** See Table 7 for load cell specifications based on the number shown.

Tables 1 through 6 are based on the performance graph for the MBZ-8.7 brake, shown in Section 2. Reference the accuracy plots, starting in section 4, for recommended load cells.
3.3 Load Cell Size

The load cell(s) for the system should be specified by their load rating (column 2 or 3). Sections 5.1 & 5.2 has the data for the listed load cells.

<table>
<thead>
<tr>
<th>Load Cell Ref. #</th>
<th>Load Rating (lbs.)</th>
<th>Load Rating (Kg.)</th>
<th>Arm (inches [cm])</th>
<th>Max Torque (in-lbs.)</th>
<th>Max Torque (Nm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2.2</td>
<td>1</td>
<td>4 [10.16]</td>
<td>8.8</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>4.4</td>
<td>2</td>
<td>4 [10.16]</td>
<td>17.6</td>
<td>2</td>
</tr>
<tr>
<td>3</td>
<td>11</td>
<td>5</td>
<td>4 [10.16]</td>
<td>44</td>
<td>5</td>
</tr>
<tr>
<td>4</td>
<td>13</td>
<td>6</td>
<td>4 [10.16]</td>
<td>52.9</td>
<td>6</td>
</tr>
<tr>
<td>5</td>
<td>22</td>
<td>10</td>
<td>4 [10.16]</td>
<td>88.5</td>
<td>10</td>
</tr>
<tr>
<td>6</td>
<td>33</td>
<td>15</td>
<td>4 [10.16]</td>
<td>132</td>
<td>15</td>
</tr>
<tr>
<td>7</td>
<td>44</td>
<td>20</td>
<td>4 [10.16]</td>
<td>176</td>
<td>20</td>
</tr>
<tr>
<td>8</td>
<td>55</td>
<td>25</td>
<td>4 [10.16]</td>
<td>220</td>
<td>25</td>
</tr>
<tr>
<td>9</td>
<td>66</td>
<td>30</td>
<td>4 [10.16]</td>
<td>264</td>
<td>30</td>
</tr>
<tr>
<td>10</td>
<td>77</td>
<td>35</td>
<td>4 [10.16]</td>
<td>308</td>
<td>35</td>
</tr>
<tr>
<td>11</td>
<td>50</td>
<td>23</td>
<td>4 [10.16]</td>
<td>200</td>
<td>23</td>
</tr>
<tr>
<td>12</td>
<td>100</td>
<td>45</td>
<td>4 [10.16]</td>
<td>400</td>
<td>45</td>
</tr>
<tr>
<td>13</td>
<td>150</td>
<td>68</td>
<td>4 [10.16]</td>
<td>600</td>
<td>68</td>
</tr>
<tr>
<td>14</td>
<td>250</td>
<td>113</td>
<td>4 [10.16]</td>
<td>1,000</td>
<td>113</td>
</tr>
<tr>
<td>15</td>
<td>500</td>
<td>226</td>
<td>4 [10.16]</td>
<td>2,000</td>
<td>226</td>
</tr>
</tbody>
</table>

Table 7: Load Cell Reference

The following sections, 4 & 5, are the specifications for the different types of load cells.
4. LOAD CELLS (DB6B-8.7T-FM, Measuring Brake Torque):

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max Brake Torque</td>
<td>250 in-lbs. (28 Nm)</td>
</tr>
<tr>
<td>Max Torque to L.C</td>
<td>277 in-lbs. (31 Nm)</td>
</tr>
<tr>
<td>Non-Linearity</td>
<td>0.02% of Rated Load (R.L.)</td>
</tr>
<tr>
<td>Hysteresis</td>
<td>0.02% of R.L.</td>
</tr>
<tr>
<td>Non-Repeatability</td>
<td>0.02% of R.L.</td>
</tr>
<tr>
<td>Zero Balance</td>
<td>±1% of R.L.</td>
</tr>
<tr>
<td>Compensated Temperature Range</td>
<td>14°F to 104°F</td>
</tr>
<tr>
<td>Safe Temperature Range</td>
<td>14°F to 140°F</td>
</tr>
<tr>
<td>Temperature Effect on Output</td>
<td>0.002% of Load/°F</td>
</tr>
<tr>
<td>Temperature Effect on Zero</td>
<td>0.002% of Load/°F</td>
</tr>
<tr>
<td>Safe Overload</td>
<td>150% of R.L.*</td>
</tr>
</tbody>
</table>
4.1 Brake Load Cell Accuracy Plot (in-lbs.) - Linear

Load Cell Rating: 278 in-lbs.
Max Brake Torque: 250 in-lbs.

Max Torque from Arm * Load Cell (20-kg) * 6.29555 \( \text{in-lbs} \)

44-lbs (20-kg) * 6.29555 \( \text{in-lbs} \) = Max. Torq.

Load Cell: 278 in-lbs.
4.2 Brake Load Cell Accuracy Plot (Nm) - Linear

Load Cell = Max Torque
20-kg (44-lbs) * 16 (cm) = 31.4 (Nm)

31.4 Nm; Max Load Cell Rating

28.2 Nm; Max Brake Torque

0.47 Nm
0.63 Nm
0.94 Nm
1.88 Nm

0.00%  1.00%  2.00%  3.00%  4.00%  5.00%

0         3         6         9        12        15       18       21       24       27       30       33

Brake Torque (Nm)
5. LOAD CELLS (DB6M-8.7T-FM, Measuring Motor Torque):

5.1 TYPE I (Low Load):

- Load Rating (lbs.) ...................................................... 2.2, 4.4, 11, 13, 22, 44, 66, 77
- Load Ratings (kg.) ...................................................... 1, 2, 5, 6, 10, 20, 30, 35
- Load Cell Arm .......................................................... 4.0 in. (10.16 cm)
- Torque Limits (in-lbs.) .................................................. 8.8, 17.6, 20, 53, 88.5, 177, 265, 309
- Torque Limits (Nm) ...................................................... 1, 2, 5, 6, 10, 20, 30, 35
- Non-Linearity .............................................................. 0.02% of R.L.
- Hysteresis ................................................................. 0.02% of R.L.
- Non-Repeatability ........................................................ 0.02% of R.L.
- Zero Balance ............................................................. ±1% of R.L.
- Compensated Temperature Range ............................... 14°F to 104°F
- Safe Temp. Range ...................................................... 14°F to 140°F
- Temp. Effect on Output .............................................. 0.002% of Load/°F
- Temp. Effect on Zero ................................................... 0.002% of Load/°F
- Safe Overload ........................................................... 150% of R.L.*

5.2 TYPE II (High Load):

- Load Rating (lbs.) ........................................................ 100, 150, 250, 500
- Load Ratings (kg.) ...................................................... 45, 68, 113, 227
- Load Cell Arm ........................................................... 4 in. (10.16 cm)
- Torque Limits (in-lbs.) ................................................. 400, 600, 1,000, 2,000
- Torque Limits (Nm) ...................................................... 45, 68, 113, 226
- Non-linearity .............................................................. 0.03% of R.L.
- Hysteresis ................................................................. 0.02% of R.L.
- Zero Balance ............................................................. ±1% of R.L.
- Operating Temperature Range ..................................... -40°F to 150°F / -40°C to 65°C
- Temp. Effect on Output .............................................. 0.002% of Load/°F
- Temp. Effect on Zero ................................................... 0.002% of Load/°F
- Safe Overload ........................................................... 150% of R.L.*

* Hard stops are in place to help prevent damage from over-load.

The Torque Accuracy plots, 5.3 through 5.6, show the percentage error as a function of measured torque. These plots show the range that a load cell will accurately measure. Plots are shown on a linear scale and, for clarity, on a logarithmic scale. The maximum torque to the motor is based on the pulley ratio selected for belt coupled systems. The error plot is based on published data from the vendor for the load cell.
5.3  Motor Load Cell Accuracy Plot (in-lbs.) – Linear

<table>
<thead>
<tr>
<th>Load Cell (lbs, kg)</th>
<th>Arm = Max Tq, (in.)</th>
<th>Max Tq, (in-lbs.)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.2 [1]</td>
<td>* 4</td>
<td>8.8</td>
</tr>
<tr>
<td>4.4 [2]</td>
<td>* 4</td>
<td>18</td>
</tr>
<tr>
<td>11 [5]</td>
<td>* 4</td>
<td>44</td>
</tr>
<tr>
<td>13 [6]</td>
<td>* 4</td>
<td>53</td>
</tr>
<tr>
<td>22 [10]</td>
<td>* 4</td>
<td>88.5</td>
</tr>
<tr>
<td>44 [20]</td>
<td>* 4</td>
<td>177</td>
</tr>
<tr>
<td>77 [35]</td>
<td>* 4</td>
<td>309</td>
</tr>
<tr>
<td>150 [68]</td>
<td>* 4</td>
<td>600</td>
</tr>
<tr>
<td>250 [113]</td>
<td>* 4</td>
<td>1,000</td>
</tr>
<tr>
<td>500 [227]</td>
<td>* 4</td>
<td>2,000</td>
</tr>
</tbody>
</table>

Air Drag Torque @ Max Brake Speed:
32 in-lbs, x 1 brake,
1:2 ratio = 16 in-lbs to motor

Max Continuous Power (13.3 HP):
69.9 in-lbs, x2 brakes,
1:1 ratio = 139.7 in-lbs to motor

Max Load - Load Cell &
Max Torque to Motor:
250 in-lbs, x2 brakes,
4:1 ratio = 2,000 in-lbs to motor

Max Continuous Power (13.3 HP):
69.9 in-lbs, x2 brakes,
4:1 ratio = 559 in-lbs to motor

Max Continuous Torque (2B):
220 in-lbs, x2 brakes,
4:1 ratio = 1,760 in-lbs to motor
5.4 Motor Load Cell Accuracy Plot (in-lbs.) – Logarithmic
5.5 Motor Load Cell Accuracy Plot (Nm) – Linear

Air Drag Torque @ Max Brake Speed:
3.6 Nm, x1 brake,
1:2 ratio = 1.8 Nm to motor

Max Continuous Power (9.92 kW):
7.9 Nm x 2 brakes,
1:1 ratio = 15.8 Nm to motor

Max Continuous Power (9.92 kW):
7.9 Nm x 2 brakes,
4:1 ratio = 63.2 Nm to motor

Max Continuous Torque (28):
24.8 Nm, x2 brakes,
4:1 ratio = 198 Nm to motor

Max Load - Load Cell & Max Torque to Motor:
28.25 Nm, x2 brakes,
4:1 ratio = 226 Nm to motor

<table>
<thead>
<tr>
<th>Load Cell (kg</th>
<th>Arm (cm)</th>
<th>Max Tq. (Nm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2.2</td>
<td>10.16 = 1</td>
</tr>
<tr>
<td>2</td>
<td>4.4</td>
<td>10.16 = 2</td>
</tr>
<tr>
<td>5</td>
<td>11</td>
<td>10.16 = 5</td>
</tr>
<tr>
<td>6</td>
<td>13</td>
<td>10.16 = 6</td>
</tr>
<tr>
<td>10</td>
<td>22</td>
<td>10.16 = 10</td>
</tr>
<tr>
<td>20</td>
<td>44</td>
<td>10.16 = 20</td>
</tr>
<tr>
<td>35</td>
<td>77</td>
<td>10.16 = 35</td>
</tr>
<tr>
<td>68</td>
<td>150</td>
<td>10.16 = 68</td>
</tr>
<tr>
<td>113</td>
<td>250</td>
<td>10.16 = 114</td>
</tr>
<tr>
<td>227</td>
<td>500</td>
<td>10.16 = 226</td>
</tr>
</tbody>
</table>
5.6 Motor Load Cell Accuracy Plot (Nm) – Logarithmic

DB6M-8.7T-FM_Torque Accuracy

various load cells measuring motor torque

04/27/20

<table>
<thead>
<tr>
<th>Load Cell (kg [lbs])</th>
<th>Arm (cm)</th>
<th>Max Tq (Nm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 [2.2]</td>
<td>10.16</td>
<td>1</td>
</tr>
<tr>
<td>2 [4.4]</td>
<td>10.16</td>
<td>2</td>
</tr>
<tr>
<td>6 [13]</td>
<td>10.16</td>
<td>6</td>
</tr>
<tr>
<td>10 [22]</td>
<td>10.16</td>
<td>10</td>
</tr>
<tr>
<td>20 [44]</td>
<td>10.16</td>
<td>20</td>
</tr>
<tr>
<td>35 [77]</td>
<td>10.16</td>
<td>35</td>
</tr>
<tr>
<td>68 [150]</td>
<td>10.16</td>
<td>68</td>
</tr>
<tr>
<td>113 [250]</td>
<td>10.16</td>
<td>114</td>
</tr>
<tr>
<td>227 [500]</td>
<td>10.16</td>
<td>226</td>
</tr>
</tbody>
</table>

Max Stall Torque (18):
14.7 Nm, x1 brake, 1:4 ratio = 3.67 Nm to motor

Max Load - Load Cell & Max Torque to Motor:
28.25 Nm, x2 brakes, 4:1 ratio = 226 Nm to motor
6. SPEED:
A standard brake has five magnets (alternative quantity or an external encoder is optional) which trigger a hall effect sensor. The speed is averaged over one revolution of the brake. A 48-MHZ clock is used to measure the time between magnets (or pulses).

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clock Error</td>
<td>~25°C</td>
<td>±30</td>
<td></td>
<td></td>
<td>PPM</td>
</tr>
<tr>
<td></td>
<td>-10°C to 60°C</td>
<td>±50</td>
<td></td>
<td></td>
<td>PPM</td>
</tr>
<tr>
<td></td>
<td>-40°C to 85°C</td>
<td>±100</td>
<td></td>
<td></td>
<td>PPM</td>
</tr>
<tr>
<td>Brake Speed</td>
<td>5 magnets</td>
<td>12</td>
<td></td>
<td>180,000*</td>
<td>RPM</td>
</tr>
<tr>
<td></td>
<td>30 magnets</td>
<td>2</td>
<td></td>
<td>30,000*</td>
<td>RPM</td>
</tr>
<tr>
<td></td>
<td>1,000 PPR</td>
<td>0.066</td>
<td></td>
<td>5,000</td>
<td>RPM</td>
</tr>
<tr>
<td></td>
<td>2,000 PPR</td>
<td>0.033</td>
<td></td>
<td>2,000</td>
<td>RPM</td>
</tr>
</tbody>
</table>

* Theoretical speed; actual maximum speed is limited to the speed of the brake.

7. SAMPLING:
This is the rate at which data is measured/recorded. This rate is adjustable by the operator.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sampling Rate</td>
<td>2.3 MHz Proc.</td>
<td>20</td>
<td>50</td>
<td></td>
<td>ms</td>
</tr>
</tbody>
</table>

A computer with a more powerful processor may allow a higher sampling frequency.

8. LAPTOP COMPUTER:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Conditions</th>
<th>Min.</th>
<th>Typ.</th>
<th>Max.</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Processor</td>
<td>2.3</td>
<td></td>
<td></td>
<td></td>
<td>GHz</td>
</tr>
<tr>
<td>Memory</td>
<td>8</td>
<td></td>
<td></td>
<td></td>
<td>GB</td>
</tr>
<tr>
<td>Display</td>
<td>LED LCD</td>
<td>15.6</td>
<td></td>
<td></td>
<td>inches</td>
</tr>
</tbody>
</table>

9. POWER REQUIREMENTS
The MBS Dynamometer requires two 115 or 230 VAC power outlets: one for the laptop computer and one for the controller. The brakes in the dynamometer structure receive power from the controller. The AC power supplies the power supplies and cooling fan in the controller; everything else is 24 VDC (or less) in the system.

<table>
<thead>
<tr>
<th>Item</th>
<th>Voltage</th>
<th>Type</th>
<th>Current (amps)</th>
<th>Freq. (Hz)</th>
<th># Plugs</th>
</tr>
</thead>
<tbody>
<tr>
<td>Controller</td>
<td>115/230</td>
<td>VAC</td>
<td>1.1/0.6</td>
<td>50/60</td>
<td>1</td>
</tr>
<tr>
<td>Laptop</td>
<td>110-240</td>
<td>VAC</td>
<td>1.2</td>
<td>50/60</td>
<td>1</td>
</tr>
<tr>
<td>Dynamometer</td>
<td>24</td>
<td>VDC</td>
<td>6.0</td>
<td>-</td>
<td>none*</td>
</tr>
</tbody>
</table>
10. DC VOLTAGE TRANSDUCERS:

10.1 Input:
Range.............................................. 0 VDC to: 1, 5, 10, 50, 150, 200 up to 600 VDC
Overload........................................ 2x voltage range selected
Frequency Range.......................... DC only

The range represents transducers that measure from 0-1 VDC, 0-5 VDC, 0-10 VDC, etc.

10.2 Output:
Basic Accuracy.............................. 1.0%
Linearity...................................... 10% to 100% F.S.
Thermal Drift.............................. 500 PPM/° C
Response Time............................. 250 ms

10.3 Environmental and Physical Characteristics:
Operating Temperature.................. 0°C to + 50°C
Insulation Category...................... CAT II
Vibration Tested to...................... IEC 60068-2-6, 1995
Pollution Degree......................... 2
Altitude...................................... 2000-meter max.
Insulation Voltage...................... 2500 VDC
MTBF......................................... Greater than 100K hours
Relative Humidity....................... 5% to 95%, non-condensing
Weight...................................... 0.5 lbs.
11. AC VOLTAGE TRANSDUCERS – SINGLE PHASE:

11.1 Input:
- Range ............................................. 0 VAC to: 50, 150, 250, 500, 600 VAC
- Overload ......................................... 2x voltage range selected
- Frequency Range ........................... 20 Hz to 5 kHz

11.2 Output:
- Basic Accuracy ............................... 0.5%
- Linearity ........................................ 10% to 100% F.S.
- Calibration ...................................... True RMS sensing
- Thermal Drift ................................. 500 PPM/°C
- Response Time .............................. 250 ms

11.3 Environmental and Physical Characteristics:
- Operating Temperature .................... 0°C to +60°C
- Insulation Category ........................ CAT II
- Vibration Tested to .......................... IEC 60068-2-6, 1995
- Pollution Degree ............................. 2
- Altitude .......................................... 2000-meter max.
- Insulation Voltage ........................... 2500 VDC
- MTBF ........................................... Greater than 100K hours
- Relative Humidity ........................... 5% to 95%, non-condensing
- Weight .......................................... 0.5 lbs.
12. AC VOLTAGE TRANSDUCERS – THREE PHASE:

12.1 Input:
- Range: 0 VAC to: 50, 150, 250, 500, 600 VAC
- Overload: 2x voltage range selected
- Frequency Range: 20 Hz to 5 kHz

12.2 Output:
- Basic Accuracy: 0.5%
- Linearity: 10% to 100% F.S.
- Calibration: True RMS sensing
- Thermal Drift: 500 PPM/°C
- Response Time: 250 ms

12.3 Environmental and Physical Characteristics:
- Operating Temperature: 0° C to +60° C
- Insulation Category: CAT II
- Vibration Tested to: IEC 60068-2-6, 1995
- Pollution Degree: 2
- Altitude: 2000-meter max.
- Insulation Voltage: 2500 VDC
- MTBF: Greater than 100K hours
- Relative Humidity: 5% to 95%, non-condensing
- Weight: 0.5 lbs.

12.4 Applications:
- Harmonic voltages
- Chopped waveform drivers
- Quickly varying voltage supplies
- Phase fired controlled devices
13. DC CURRENT TRANSDUCERS (Split Core):

13.1 Input:
Range (0 ADC up to) .................. 2, 5, 10, 20, 30, 50, 75, 100, 150, 300 ADC
Overload ................................... 4x current range selected
Frequency Range ....................... DC only

13.2 Output:
Basic Accuracy ......................... 1.0%
Linearity ................................. 10% to 100% F.S.
Thermal Drift ............................. 500 PPM/° C
Response Time ......................... 250 ms

13.3 Environmental and Physical Characteristics:
Operating Temperature ............... 0°C to +50°C
Insulation Category ..................... CAT II
Vibration Tested to ..................... IEC 60068-2-6, 1995
Pollution Degree ....................... 2
Altitude .................................. 2000-meter max.
Insulation Voltage ..................... 2500 VDC
MTBF ..................................... Greater than 100K hours
Relative Humidity ..................... 5% to 95%, non-condensing
Weight .................................. 0.5 lbs.
14. AC CURRENT TRANSDUCERS – SINGLE PHASE (Split Core):

14.1 Input:
- Range (0 AAC up to) ................. 5, 10, 15, 20, 25, 30, 40, 50, 75, 100...600 AAC
- Overload .................................. 4x current range selected
- Frequency Range ...................... 20 Hz to 5 kHz

14.2 Output:
- Basic Accuracy ...................... 0.5%
- Linearity .................................. 10% to 100% F.S.
- Calibration ............................... True RMS sensing
- Thermal Drift ........................... 500 PPM/°C
- Response Time ......................... 250 ms

14.3 Environmental and Physical Characteristics:
- Operating Temperature .............. 0°C to + 60°C
- Insulation Category .................. CAT II
- Vibration Tested to .................... IEC 60068-2-6, 1995
- Pollution Degree ....................... 2
- Altitude .................................... 2000-meter max.
- Insulation Voltage ..................... 2500 VDC
- MTBF ...................................... Greater than 100K hours
- Relative Humidity ..................... 5% to 95%, non-condensing
- Weight ..................................... 0.5 lbs.
15. AC CURRENT TRANSDUCERS – THREE PHASE (Low Current):

15.1 Input:
- Range (0 up to): 0.5, 5, 10, 15, 16, 20, 25 AAC
- Overload: 4x current range selected
- Frequency Range: 20 Hz to 5 kHz

15.2 Output:
- Basic Accuracy: 0.5%
- Linearity: 10% to 100% F.S.
- Calibration: True RMS sensing
- Thermal Drift: 500 PPM/°C
- Response Time: 250 ms max., 0 - 90%

15.3 Environmental and Physical Characteristics:
- Operating Temperature: 0°C to +60°C
- Insulation Category: CAT II
- Vibration Tested to: IEC 60068-2-6, 1995
- Pollution Degree: 2
- Altitude: 2000-meter max.
- Insulation Voltage: 2500 VDC
- MTBF: Greater than 100K hours
- Relative Humidity: 5% to 95%, non-condensing
- Weight: 0.5 lbs.
16. AC CURRENT TRANSDUCERS – THREE PHASE (High Current):

16.1 Input:
Range (0 up to) .................. 150, 200, 250, 400, 500, 600, 800, 1000 AAC
Overload (per range selected) ....... 600, 750, 800, 1000, 1200, 1200, 1500 AAC
Frequency Range ................... 47 to 63 Hz

16.2 Output:
Current Signal .................. 4 to 20 mA-DC (Full Scale)
Accuracy ...................... (Over the temperature range) ±0.5% F.S.
............................................... max (±100 mA)

(Specified accuracy includes the combined worst-case effects of 4mA Offset,
Temperature, Hysteresis, Supply Swings and Current Cable Positioning.)

Ripple .......................... 0.2% max (40 uA-AC)
Response Time (10 to 90%) ........ 300 ms
Load Resistance (RL) ............... 250 Ohms Nominal (0-300 Ohms Range)
Crest Factors ...................... 0 to 5
Current Signal @ Overload .......... 23 mA-DC typical
Output Protection .............. Reverse Polarity Protection

16.3 Environmental and Physical Characteristics:
Operating Temperature Range ........ -40°C to +85°C
Conducted Susceptibility .......... DO-160E Section 20 (1.5 Ma @ 10KHz to
................................................... 75 Ma @ 500 kHz to 400 MHz
Transient Burst (EN 50155) ......... ±2KV Open CKT test voltage supply leads
Electrostatic Discharge (ESD) ...... DO-160E Section 25 Category A
Humidity (Operating) ............. 0% to 100% R.H.
Moisture Resistance ............... MIL-STD-202 Method 106
Random Vibration (Operating) ...... MIL-STD-810F, Proc.1, Cat.12, WO=0.095G2/Hz,
................................................... Time1 hr., Overall Level 12.G-RMS
Shock .......................... 50g 11m-sec. half sine pulse
Isolation .......................... Input to output 5KV RMS 60 Hz/1min.
Insulation Resistance .......... 500 M-Ohms @ 100 VDC
Case Material ................. Brass
Finish .......................... Fuse tin plate per ASTM-B-545
Weight ......................... 4 lbs. Max
19. DYNAMOMETER LAYOUT – DB6M-8.7T-FM
20. MOTOR MOUNTING PLATE – DB6M
21. CONTROLLER – DYNAMOMETER, TANDEM

![Diagram of Controller - Dynamometer, Tandem]

**NOTES:**
1. CONTROLLER WEIGHT: 24 LBS.
2. VOLTAGE: 15/20/30 AMPS
3. CURRENT: 12/9/7 AMPS
4. LOAD CELL AND SPEED SIGNAL OUTPUTS (OPTIONAL)
5. D/D/O SWITCH (INTERNAL POWER RECEPTACLE)
6. COOLING FAN
7. USB (TO PC)
8. REMOTE SIGNALS (NOTE 3)
9. INPUTS & OUTPUTS TO DYNAMOMETER

---

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20. NOMENCLATURE OF DYNAMOMETER MODEL NUMBER

DB6M-8.7T-FM

Motor Mounting Style:
FM = Face Mount
BM = Base Mount
CB = Carriage Base

Number of Brakes:
T = Tandem System
Omitting T = single brake system

Brake Size:
17.5 = MBZ-17.5 brake
8.7 = MBZ-8.7 brake
5.7 = MBZ-5.7 brake
3.7 = MBZ-3.75 brake
2.4 = MBZ-2.4 brake

Load Cell Location:
M = Measuring Motor Torque
B = Measuring Brake Torque

Centerline Distance:
5 = 5 inches from top of baseplate to centerline of motor shaft.
6 = 6 inches from top of baseplate to centerline of motor shaft

System Type:
B = Belt Coupled system
I = Inline system
D = Dynamometer

The load cell(s) size(s) and type(s) of voltage & Current transducers are to be specified individually.